

**Time and Place:** 13:20–14:20, March 6, 2022, Yokohama

**Speaker:** Osamu Kobayashi

**Title:** On an endnote of “A profile of Prof. Masaaki Umehara and Prof. Kotaro Yamada’s achievements”

**Abstract:** The speaker would like to discuss endnote 29 of an article of Sugaku 73, MSJ, of the title.

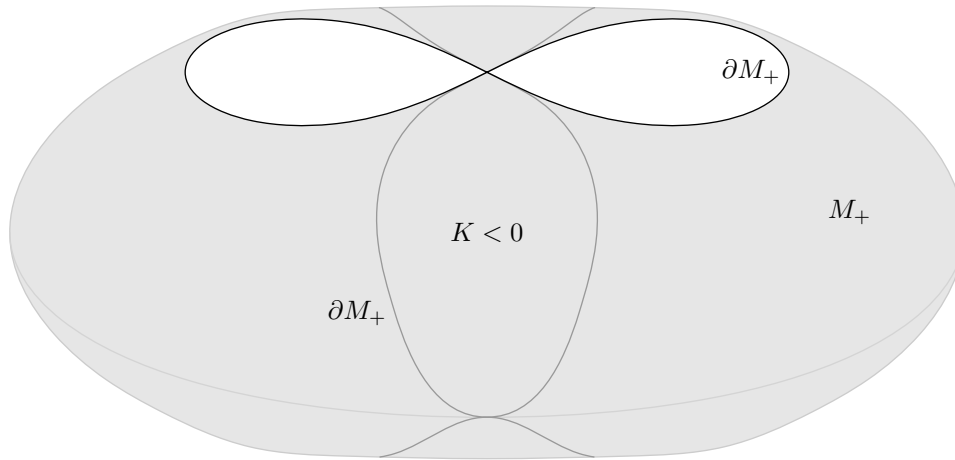


Figure 21915.  $M : \left( (x^2 + y^2)^2 + 4xy + 1 \right) (4 - \sqrt{9 - 16z^2}) = 4$

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# 1 The Herglotz integral formula and rigidity theorems

## 1.1 Notation and terminology

1. **compact connected surface**  $(M, g)$

—  $M$  may have boundary  $\partial M$  but we often tacitly assume  $\partial M = \emptyset$ .

2. **the Gauss curvature**  $K = K_g$

$$M_+ = \overline{\{x \in M \mid K(x) > 0\}}$$

3. **the traceless part of**  $E = \{A \in T^*M \otimes T^*M \mid A(X, Y) = A(Y, X)\}$

$$\begin{aligned} \overset{\circ}{E} &= \{A \in E \mid \text{tr } A = 0\} \\ A &= \frac{1}{2}(\text{tr } A)g + \overset{\circ}{A} \\ \hat{A} &= \frac{1}{2}(\text{tr } A)g - \overset{\circ}{A} \end{aligned}$$

4. **the cofactor tensor**  $\hat{A}$  of  $A$ :  $J \in \text{End}(TM)$  is such that  $J^2 = -1$  and  $\text{tr}_g J = 0$ .

$$\begin{aligned} \hat{A}(X, Y) &= A(JX, JY) \\ \langle \hat{A}, A \rangle &= 2 \det A \end{aligned}$$

5. **Codazzi tensor**  $A \in \Gamma(E)$ :

$$\begin{aligned} \nabla_X A(Y, Z) &= \nabla_Z A(Y, X) \\ \text{div } \hat{A} &= (A^i_{j;i}) = 0 \end{aligned}$$

6. **The determinant norm of  $E$  or polarization of  $\det$ :**

$$((A, B)) := \det_g \left( \frac{A+B}{2} \right) - \det_g \left( \frac{A-B}{2} \right) = \frac{1}{2} \langle \hat{A}, B \rangle, \quad \text{sgn} = (+ - -)$$

7. **conformal classes**  $[\theta]$  and  $[\theta]_+$ ,  $\theta \in \Gamma(E)$ :

$$\begin{aligned} [\theta] &= \{v\theta \in \Gamma(E) \mid v \in C^\infty(M)\} \\ [\theta]_+ &= \{e^{2u}\theta \in \Gamma(E) \mid u \in C^\infty(M)\} \subset [\theta] \end{aligned}$$

8.  $\theta \in \Gamma(E)$  is **within range of  $g$**   $\stackrel{\text{def}}{\iff} \exists \eta \in \Gamma(TM)$  such that

$$g + \frac{1}{2}L_\eta g \in [\theta]_+.$$

9.  $E^\delta$ ,  $\delta \in C^\infty(M)$  and  $E_\theta$ ,  $\theta \in \Gamma(E^\delta) \subset \Gamma(E)$

$$E^\delta := \{\theta \in E \mid \det_g \theta = \delta\}, \quad E_\pm^\delta := \{\theta \in E^\delta \mid \theta \text{ is positive/negative definite}\}$$

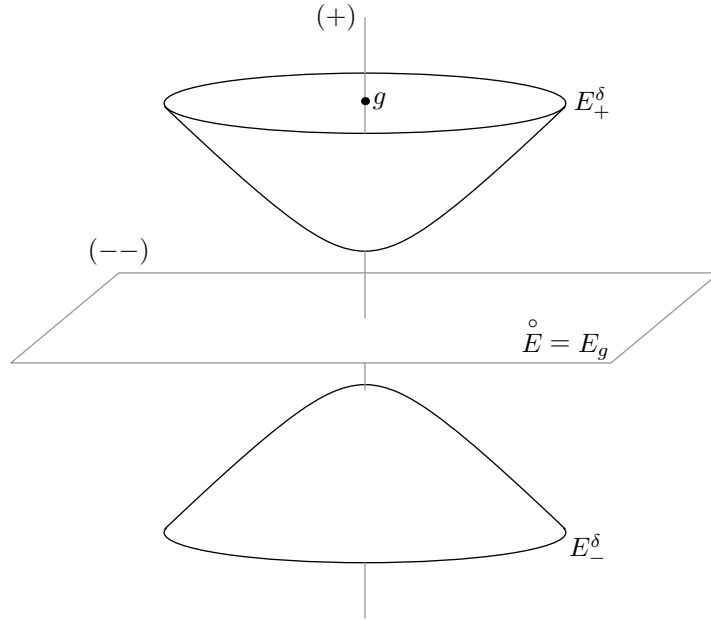


Figure 1  $E \cap (T_p^*M \otimes T_p^*M)$ ,  $\delta > 0$

$$E_\theta := \{A \in E \mid ((\theta, A)) = 0\} \simeq T_\theta E^\delta$$

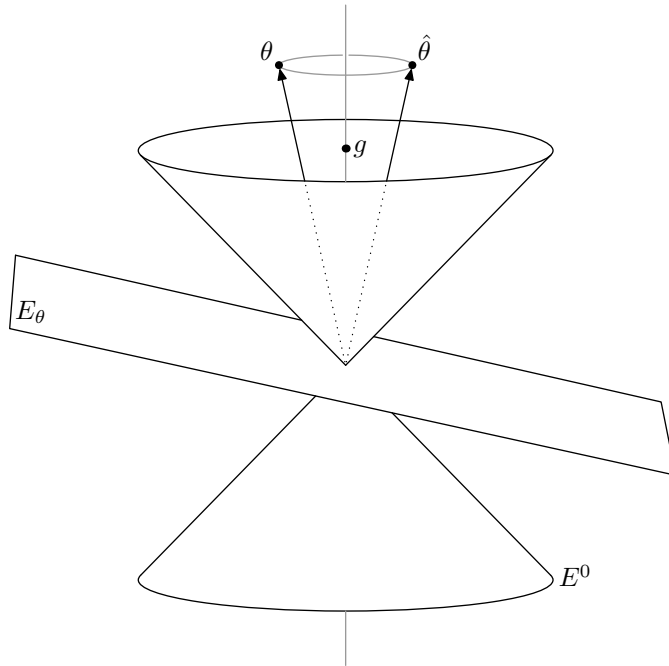


Figure 2  $E_\theta \parallel T_\theta E^{\det \theta}$ ,  $\det \theta > 0 \Rightarrow ((, ))|_{E_\theta} < 0$ .

## 1.2 The Herglotz formula

**Proposition 1.1** (The Herglotz integral formula).  $\nu$  denotes the outward unit normal along  $\partial M$ .

Assume :  $\theta_i \in \Gamma(E^\delta)$  are Codazzi tensors, and  $g + \frac{1}{2}L_{\eta_i}g = v_i\theta_i$ ,  $i = 1, 2$ .

$$\text{Then : } \int_M (v_1 + v_2) \det(\theta_1 - \theta_2) d\mu = \int_{\partial M} (\hat{\theta}_1 - \hat{\theta}_2)(\nu, \eta_1 - \eta_2) ds.$$

*Proof.* From (1) and (2) below and the divergence theorem:

$$(1) (v_1 + v_2) \det(\theta_1 - \theta_2) = ((\theta_1 - \theta_2, L_{\eta_1 - \eta_2}g)):$$

$$r.h.s. = ((\theta_1 - \theta_2, 2(v_1\theta_1 - v_2\theta_2))) = ((\theta_1 - \theta_2, (v_1 + v_2)(\theta_1 - \theta_2))) = l.h.s. \text{ because } \det \theta_1 = \det \theta_2 = \delta.$$

$$(2) ((\theta_1 - \theta_2, L_{\eta_1 - \eta_2}g)) = \text{div}((\hat{\theta}_1 - \hat{\theta}_2)(\cdot, \eta_1 - \eta_2)):$$

$$((\theta_1 - \theta_2, L_{\eta_1 - \eta_2}g)) = \left\langle \hat{\theta}_1 - \hat{\theta}_2, \frac{1}{2}L_{\eta_1 - \eta_2}g \right\rangle = \left\langle \hat{\theta}_1 - \hat{\theta}_2, \nabla(\eta_1 - \eta_2) \right\rangle \text{ and } \text{div}(\hat{\theta}_1 - \hat{\theta}_2) = 0.$$

□

**Lamma 1.2.**  $\det \theta_1 = \det \theta_2 \Rightarrow \theta_1 - \theta_2 \in E_{\theta_1 + \theta_2}$ .

*Proof.*  $((\theta_1 + \theta_2, \theta_1 - \theta_2)) = ((\theta_1, \theta_1)) - ((\theta_2, \theta_2)) = \det \theta_1 - \det \theta_2 = 0$ .

□

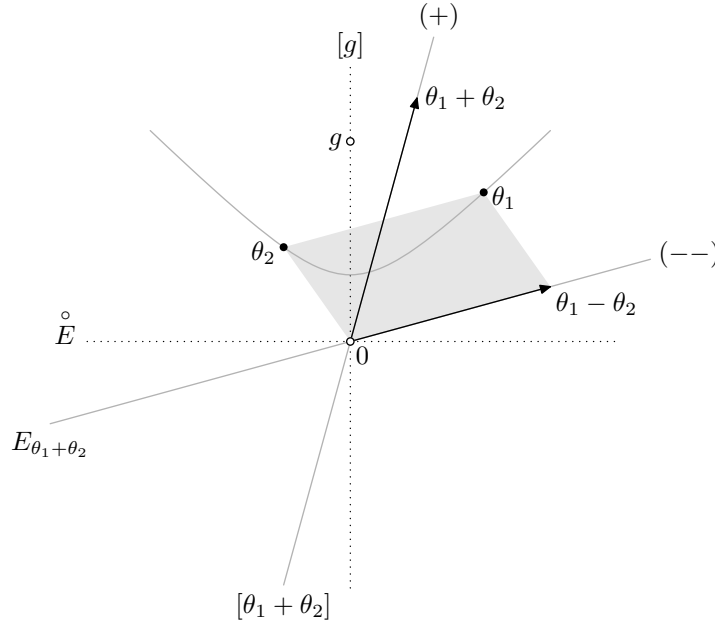


Figure 3  $\theta_1 + \theta_2 \perp_{\det} \theta_1 - \theta_2$  in  $E$

**Corollary 1.3.**  $\det \theta_1 = \det \theta_2$  and  $\det(\theta_1 + \theta_2) > 0 \Rightarrow \det(\theta_1 - \theta_2) < 0$  unless  $\theta_1 = \theta_2$ .

*Proof.*  $((, ))$  is negative definite on  $E_{\theta_1 + \theta_2}$  (Figure3).

□

**Proposition 1.4** (The Herglotz integral formula in practicable form).

Assume :

- (i)  $\det \theta_1 = \det \theta_2 > 0$ ;
- (ii) both  $\theta_1$  and  $\theta_2$  are Codazzi tensors;
- (iii) both  $\theta_1$  and  $\theta_2$  are within range of  $g$ ;
- (iv) if  $M$  has boundary,
  - $\det \theta_1 = \det \theta_2 = 0$  on  $\partial M$  ((i) overridden) and
  - $\partial M$  consists of curves whose tangent is the nullity of both  $\theta_1$  and  $\theta_2$ .

Then : either  $\theta_1 = \theta_2$  or  $\theta_1 = -\theta_2$ ;

*Proof.* Replace  $\theta_2$  by  $-\theta_2$  if necessary, and we may assume  $\det(\theta_1 + \theta_2) > 0$ .

(iv)  $\Rightarrow$  the boundary integral of Proposition 1.1 = 0 since  $\hat{\theta}_i(\nu, \cdot) = \theta_i(J\nu, J\cdot) = 0$  on  $\partial M$ .

(iii)  $\Rightarrow \int_M (v_1 + v_2) \det(\theta_1 - \theta_2) d\mu = 0$  with  $v_1 + v_2 > 0$ .

Corollary 1.3  $\Rightarrow \theta_1 = \theta_2$ . □

### 1.3 Rigidity theorems

**Lamma 1.5** (Hadamard). *If  $\partial M = \emptyset$  and  $K > 0$ , the 2nd fundamental form of an isometric immersion of  $M$  in  $\mathbf{R}^3$  is within range of  $g$  (Figure 4).*

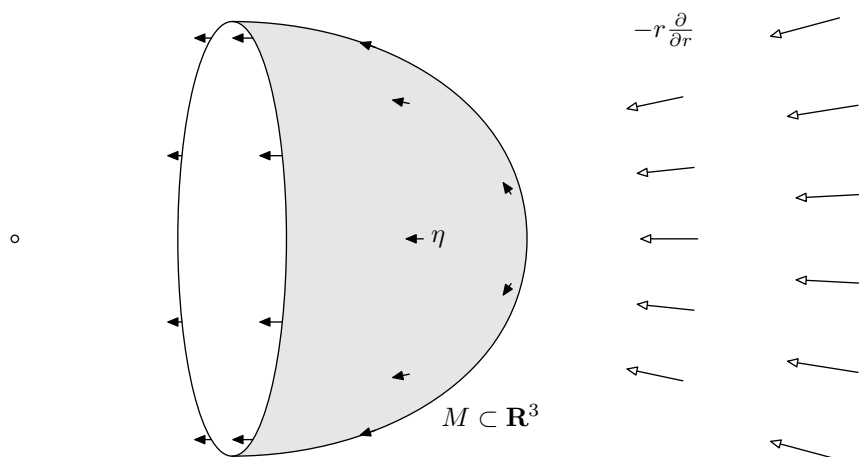


Figure 4 The condition (iii):  $\eta \in \Gamma(TM)$  is the orthogonal projection of  $-r \frac{\partial}{\partial r}$  to  $TM$ .

**Theorem 1.6** (Cohn-Vossen 1927, Herglotz 1943). *A closed surface in  $\mathbf{R}^3$  with  $K > 0$  is rigid.*

— pou sto:  $\partial M = \emptyset$ ,  $M \subset \mathbf{R}^3$  (immersion)  $\Rightarrow M_+ \neq \emptyset$ .

**Lemma 1.7** (Kuiper). *If  $M_+ \subset \mathbf{R}^3$  is connected and  $\int_{M_+} K d\mu = 4\pi$ , the 2nd fundamental form of  $M_+$  is within range of  $g$  and  $\partial M_+$  consists of curvature lines of principal curvature 0 (Figure 5).*

*Proof.* The image of the Gauss map of  $\partial M_+$  contains only finitely many points by Kuiper's tightness argument which extends the Hadamard theorem (Lemma 1.5). □

**Theorem 1.8** (Alexandrov 1938). *If  $M_+ \subset \mathbf{R}^3$  is connected and  $\int_{M_+} K d\mu = 4\pi$ ,  $M_+$  is rigid.*

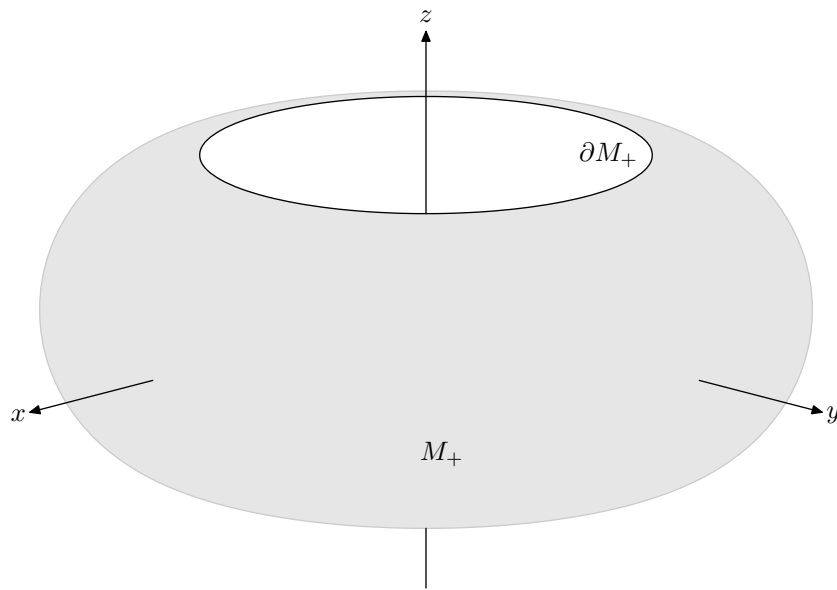


Figure 5  $M_+ : \sqrt{x^2 + y^2} - \sqrt{1 - z^2} = \sqrt{2}$

...

Theorem 1.8 says that the maximal region  $M_+$  of positively curved part of a surface has a tendency to be unbendable. Moreover in some examples the rigidity property of  $M_+$  spreads over the whole of  $M$ .

**Theorem 1.9** (Nirenberg 1963). *A torus of revolution is rigid.*

...

## References

- W. Klingenberg, Eine Vorlesung über Differentialgeometrie, Springer, 1973.  
日本語訳: 小島守男, 微分幾何学, 海外出版貿易, 1975.
- M. Spivak, A comprehensive introduction to differential geometry, Publish or Perish, 1975.

## 2 An intrinsic formulation

### 2.1 $\Sigma(M, g, \delta)$

**Definition 2.1.** (i) For  $\delta \in C^\infty(M)$ ,

$$\begin{aligned}\Sigma^\delta &= \Sigma(M, g, \delta) = \{\theta \in \Gamma(E^\delta) \mid \Lambda^\delta \theta = 0\}, \\ \Lambda^\delta &: \Gamma(E^\delta) \rightarrow \Gamma(TM); \quad \Lambda^\delta \theta = \operatorname{div} \hat{\theta} = (\hat{\theta}_i^j{}_{;j}).\end{aligned}$$

(ii) (the linearization of  $\Lambda^\delta$ ) For  $\theta \in \Gamma(E^\delta)$ ,

$$\lambda_\theta: \Gamma(E_\theta) \rightarrow \Gamma(TM); \quad \lambda_\theta \alpha = \operatorname{div} \hat{\alpha}$$

(iii)  $C: \Gamma(E \setminus E^0) \rightarrow \Gamma(TM)$ ;

$$C(\theta) = \frac{\theta(\operatorname{div} \hat{\theta}, \cdot)}{\det \theta}$$

depends only on  $[\theta]_+$ . We say  $[\theta]_+$  is a *conformally Codazzi class* if  $dC(\theta) = 0$ .

**Lemma 2.2.** (i)  $c \in \mathbf{R}, \theta \in \Sigma^\delta \Rightarrow c\theta \in \Sigma^{c^2\delta}$ .

(ii)  $[\theta]$  contains at most one Codazzi tensor up to a constant multiple.

(iii) For  $\theta \in \Gamma(E \setminus E^0)$ ,

$$\exists \text{ Codazzi tensor } \in [\theta]_+ \iff [\theta]_+ \text{ is a coformally Codazzi class and } [C(\theta)] = 0 \in H^1(M, \mathbf{R}).$$

(iv) The formal adjoint of  $\lambda_\theta$  is given as  $\lambda_\theta^* \eta = -\frac{1}{2} \widehat{L_\eta g} + v \hat{\theta}$ ,  $v = \frac{1}{|\theta|^2} \langle \theta, \nabla \eta \rangle$ .

(v)  $\ker \lambda_\theta^* = \{\eta \in \Gamma(TM) \mid L_\eta g \in [\theta]\}$ .

...

• Relation to the surface theory:  $N(k)$  denotes 3-dim space form of constant curvature  $k$

$$(\text{the 2nd f.f. of } (M, g) \rightarrow N(k)) \in \Sigma(M, g, K_g - k).$$

• Rigidity & Unbendability:

$$\begin{aligned}\theta \in \Gamma(E^\delta) \text{ is 'rigid'} &\leftarrow \Sigma(M, g, \delta) = \{\pm\theta\} \\ \theta \in \Gamma(E^\delta) \text{ is 'unbendable'} &\leftarrow \ker \lambda_\theta = 0 \text{ (near } \theta)\end{aligned}$$

...

**Proposition 2.3.** Assume  $\partial M = \emptyset$ .

(i)  $\chi(M) \neq 0 \Rightarrow \Sigma(M, g, -1) = \emptyset$ .

(ii)  $\chi(M) \neq 0 \Rightarrow \Sigma(M, g, 0) = \{0\}$ .

(iii)  $\chi(M) \leq 0 \Rightarrow \{\pm g\} \subset \Sigma(M, g, 1)$  strictly, and  $\dim \ker \lambda_g = \max\{2, -3\chi(M)\}$ .

*Proof.* (i): Poincaré-Hopf. (ii): ruled surface theorem & singular ODE.

(iii): Riemann-Roch & orientatioin coveing trick. □

The standard product metric  $g$  of  $T^2$  is a counterexmples for the converses of (i) and (ii).

## 2.2 Convexity conditions

Recall:

$$[\theta]_+ = \{e^{2u}\theta \in \Gamma(E) \mid u \in C^\infty(M)\} \subset [\theta] = \{v\theta \in \Gamma(E) \mid v \in C^\infty(M)\}$$

and

$$\begin{aligned} \theta \in \Gamma(E) \text{ is within range of } g &\stackrel{\text{def}}{\iff} \exists \eta \in \Gamma(TM); g + \frac{1}{2}L_\eta g \in [\theta]_+ \\ &\iff \exists \eta \in \Gamma(TM), \exists v \in C^\infty(M), v > 0; g + \frac{1}{2}L_\eta g = v\theta. \end{aligned}$$

Obviously

$$\theta \in [g]_+ \text{ is within range of } g.$$

This is a special case of the following:

**Proposition 2.4.** *The following are sufficient conditions for  $\theta$  to be within range of  $g$ .*

(i)  $\theta$  is the 2nd fundamental form of  $M \times \{0\}$  in  $M \times \mathbf{R}$  with the metric of the form

$$G = e^{-2t} (\alpha^2 dt^2 + dt \otimes \eta + \eta \otimes dt + g), \quad \alpha^2 = \pm v^2 + |\eta|^2.$$

$\theta$  is a Codazzi tensor if and only if  $\text{Ric}_G \left( \frac{\partial}{\partial t} - \eta, X \right) = 0$ ,  $X \in TM$ .

(ii)  $\theta$  is a Codazzi tensor and

$$\begin{aligned} v_{;ij} - \frac{1}{\delta} \theta_{li;j} \hat{\theta}^{lk} v_{;k} + \left( \log \frac{\delta}{K} \right)_{;j} v_{;i} + \frac{K}{\delta} ((\text{tr } \theta) \theta_{ij} - \delta g_{ij}) v \\ = \frac{1}{\delta} \theta_{il} \left( K g^l_j - K \alpha^l_j + \frac{K_{;j}}{K} \alpha^{lk}_{;k} - \alpha^{lk}_{;kj} \right) \end{aligned}$$

holds for some 2-form  $\alpha$  and  $v > 0$  where  $\delta = \det \theta$ .

(iii)  $\partial M = \emptyset$ ,  $\det \theta > 0$  and for some  $v > 0$  the Minkowski formula

$$\frac{1}{2} \int_M \text{tr } \alpha \, d\mu = \int_M v((\alpha, \theta)) \, d\mu$$

holds for all Codazzi tensor  $\alpha$ .

...

(i): comparable to Hadamard's convexity theorem (Lemma 1.5):

$$\frac{1}{2} L_{\frac{\partial}{\partial t}} G = -G \iff \frac{1}{2} L_{-r \frac{\partial}{\partial r}} G_0 = -G_0, \quad G_0 = dx^2 + dy^2 + dz^2$$

(ii): an integrability condition for the vector field  $\eta$  (cf. Lemma 2.2 (iii)).

(iii): We rely upon the theory of elliptic PDE.

...

Corollary 1.3 and thus Proposition 1.4 (i) are relevant to the ellipticity of  $\Lambda^\delta$  or  $\lambda_\theta$  for  $\theta \in \Gamma(E^\delta)$ .



## 2.3 Ellipticity

**Proposition 2.5.** (i)  $\lambda_\theta$  is elliptic  $\iff \det \theta > 0$ .

(ii)  $\partial M = \emptyset$  and  $\det \theta > 0 \implies \dim \ker \lambda_\theta = \dim \ker \lambda_\theta^* - 3\chi(M)$ .

*Proof.* (i): The symbol of  $\lambda_\theta$  has non-trivial kernel  $\iff \exists \xi \neq 0; ((\theta, \xi \otimes \xi)) = \hat{\theta}(\xi, \xi) = 0 \iff \det \theta \leq 0$ .

(ii): Atiyah-Singer index formula.\*<sup>1</sup> □

**Corollary 2.6.**  $M = S^2$  or  $\mathbf{RP}^2 \implies \ker \lambda_g = 0$ .

*Proof.* From Lemma 2.2 (v),  $\dim \ker \lambda_g = \dim \text{Conf}(M, g) = 3\chi(M)$  for  $M = S^2, \mathbf{RP}^2$ . □

Standard proof uses Weizenböck formula  $|\nabla \hat{\alpha}|^2 + 2K|\hat{\alpha}|^2 = \frac{1}{2}|\nabla \text{tr } \alpha|^2 - (\hat{\alpha}^{ij} \alpha_{ij};k);k + (\hat{\alpha}^{ij} \alpha_{ik};k);j$  and the formulas  $-\Delta \rho + K_g = e^{2\rho} \tilde{K}$  and  $\text{div } \hat{\alpha} - (\text{tr}_g \alpha) d\rho = e^{2\rho} \text{div } \hat{\alpha}$  for  $\tilde{g} = e^{2\rho} g$ .

**Theorem 2.7.** If  $M = S^2$  or  $\mathbf{RP}^2$  there is a neighborhood  $U \subset \Gamma(E_+)$  of  $[g]_+$  such that  $\Sigma(M, g, \det \theta) \cap U = \{\pm \theta\}$  for  $\theta \in U$ .

*Proof.* Apply the implicit function theorem to

$$\Psi: \text{Diff}(M) \times C^\infty(M) \rightarrow \Gamma(E_+); \Psi(\phi, u) = e^{2u} \phi^* g$$

at (id, 1) (Figure 6) and the Herglotz formula (Proposition 1.4). □

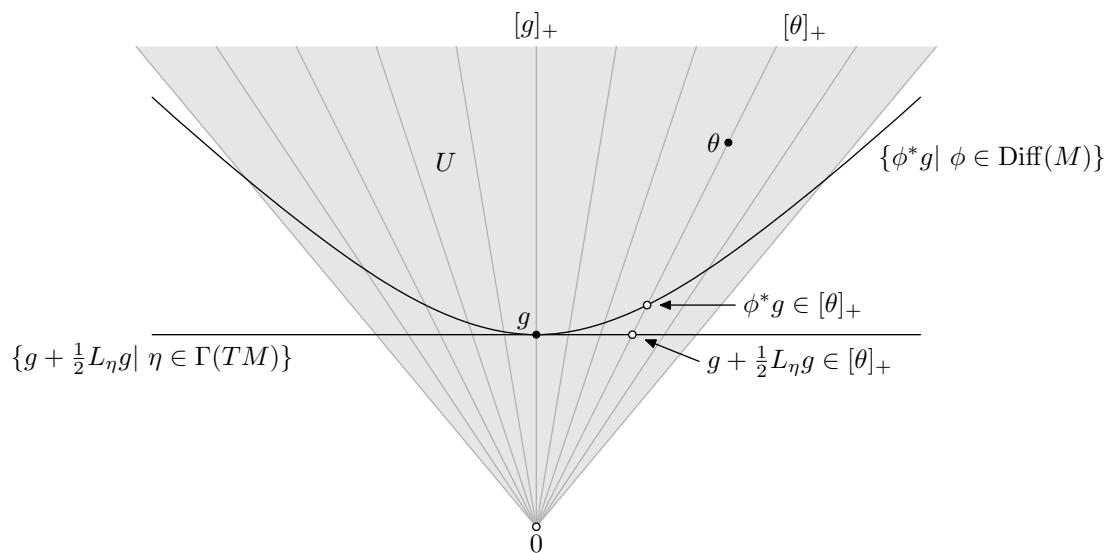


Figure 6 The orbit of  $g \in \Gamma(E_+)$  by  $\text{Diff}(M)$  and its tangent space for  $M = S^2$  or  $\mathbf{RP}^2$

**Question 2.8.** What is the Obata equation for  $\ker \lambda_\theta^*$ ?

\*<sup>1</sup> M. F. Atiyah and I. M. Singer, The index of elliptic operators on compact manifolds, Bull. Amer. Math. Soc. 69 (1963), 422–433.

### 3 The frontispiece

Figure 21915 shows the outer part of the closed surface

$$\left( (x^2 + y^2)^2 + 4xy \right)^2 + \left( (x^2 + y^2 + 1)^2 - 2(x - y)^2 \right)^2 (z^2 - d^2) = 0$$

of genus 2 with  $d = \frac{3}{4}$ . This surface  $M$  is a union of Cassini ovals and the boundary  $\partial M$  is a pair of lemniscates of Bernoulli which are curvature lines of principal curvature zero and whose nodes are umbilic points of index  $-1$ . As is obvious from the figure and Lemma 1.5 the 2nd fundamental form is within range of the 1st fundamental form. If  $\frac{3}{4} \leq d < 1$ ,  $M_+$  is connected. Its boundary  $\partial M_+$  contains  $\partial M$  and other branch components from the two umbilic points which enclose negatively curved region. Accordingly the total curvature of  $M_+$  exceeds  $4\pi$ . It is interesting to know whether the surface  $M$  is bendable or not.

Proposition 2.3 (ii), Proposition 2.5 (i) and also Lemma 2.2 (ii) suggest to intuition that asymptotic curves (not drawn in the figure) in the region where  $K < 0$  mediate regularity property which stiffens the surface. So we ignore for a while the problem arising from negatively curved part. Then what we are interested in is how to formulate Lemma 1.7 in the style of §2. It may be appropriate to think of  $M_+$  to be the closure of  $\{x \in M \mid \delta(x) > 0\}$ . We see however from Lemma 2.2 (i) that the condition  $\int_{M_+} \delta d\mu = 4\pi$  does not imply that the nullity of  $\theta \in \Sigma^\delta$  on  $\partial M_+$  is tangent to  $\partial M_+$  even if  $M_+$  is connected, and moreover if  $\theta \in \Sigma^\delta$  is within range of  $g$ . We need at least some adjustment of  $\theta \in \Sigma^\delta$  by scaling. From another point of view  $\theta \in \Sigma^\delta$  is a Riemannian metric of the interior  $\overset{\circ}{M}_+$ . In the situation of Lemma 1.7 we see that  $\theta/\delta = h/K$  is a complete metric of  $\overset{\circ}{M}_+$  whose area-growth is of length order if  $\theta \neq 0$  on  $\partial M_+$ .

To deal with bendability question, it may be easier to consider things infinitesimally. Let  $\{h_t \in \Sigma^\delta\}$  be smooth 1-parameter family and  $\theta = h_0$ ,  $\dot{\theta} = \frac{d}{dt} h_t|_{t=0}$ ,  $\ddot{\theta} = \frac{d^2}{dt^2} h_t|_{t=0, \dots}$ ,  $\theta^{(k)} = \frac{d^k}{dt^k} h_t|_{t=0}$ . That is, we have the following expansion

$$h_t = \theta + t\dot{\theta} + \frac{t^2}{2}\ddot{\theta} + \frac{t^3}{3!}\theta^{(3)} + \dots + \frac{t^k}{k!}\theta^{(k)} + \dots$$

Then  $\text{div } \hat{\theta}^{(k)} = 0$ ,  $((\dot{\theta}, \theta)) = 0$  and  $((\ddot{\theta}, \theta)) = -\det \dot{\theta}$ . These equalities are enough to rewrite Proposition 1.1 for infinitesimal deformations. This also makes it clearer that the Herglotz formula is a higher order variation of the Minkowski formula. Still higher variations are obtained from

$$\begin{aligned} ((\ddot{\theta}, \theta)) &= -\delta_1 & ((\theta^{(3)}, \theta)) &= -\frac{3}{2}\dot{\delta}_1 \\ ((\theta^{(4)}, \theta)) &= -2\ddot{\delta}_1 + \delta_2 & ((\theta^{(5)}, \theta)) &= -\frac{5}{2}\delta_1^{(3)} + \frac{5}{2}\dot{\delta}_2 \\ ((\theta^{(6)}, \theta)) &= -3\delta_1^{(4)} + \frac{9}{2}\ddot{\delta}_2 - \delta_3 & ((\theta^{(7)}, \theta)) &= -\frac{7}{2}\delta_1^{(5)} + 7\delta_2^{(3)} - \frac{7}{2}\dot{\delta}_3 \\ &\dots & & \end{aligned}$$

where  $\delta^{(k)} = \det \theta^{(k)}$ .

Not only in some details but also on the whole we find situations analogous to zero mean curvature surfaces in Minkowski 3-space. The expansion from  $M_+$  to whole  $M$  may be compared to a maximal surface in Minkowski 3-space which extends to a zero mean curvature surface with transition from spacelike part to timelike part.

...

#### 4 In place of closing

**Etwas drängend**

1 *pp*

6 *rit.* *molto rit.* *Sehr gesangvoll* *ppp* *pp*

11

17 *Poco rit.* *a tempo*

23

28

*pp*

*poco accel.* *poco rit.* Zurückhaltend

34

*pp*

*poco accel.* *poco rit.* Zurückhaltend

40

*p*

Breit. accel.

45

*mf*

Rubato rit.

51

*ff* *mf* *fff* *p*

accel.

56

*p*

3

3

*p*

62

**molto riten.**

71

**Langsam**

75

**Sehr zurückhaltend  
Sehr langsam u. immer noch  
mehr zurückhaltend**

76

*pp*

*pp*

80

**Molto rit.**

**a Tempo**

3

3

83 **Poco acceler.**

*p*

87 **Molto rit.** **Wieder sehr langsam, wie zurvo**

*p*

90 **Sehr langsam**

*ppp* *pp*

96 **rit.**

*pp subito*

102

108 **Zurückhaltend** **Tempo Sehr breites**  
**Alla breve**

*pp poco cresc. p*

115 **Etwas drängend**

*pp*

**Wieder zurückhaltend** **Tempo Noch breiter als vorher**

*p poco cresc. molto cresc. ff*

126 **Più mosso**

*ff fff*

**poco accel.** **Tempo I.**

*dim. mf molto dim. pp*

138

*p*

145

*pp*

149

*8va*

153

*8va*

The image shows a piano score for measures 138 to 153 of Mahler's Symphony No. 1. It consists of four systems of music, each with a treble and bass staff. Measure 138 starts with a piano (*p*) dynamic. Measure 145 starts with a pianissimo (*pp*) dynamic. Measures 149 and 153 feature an octave shift (*8va*) in the treble staff. The bass staff contains sustained chords and moving lines, often with a wavy line underneath. The treble staff contains melodic lines, some with slurs and ties.

Figure 787 : From symphony no.1 by G. Mahler

